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**By Chanel Ashby**

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Game theory using physical constraints, time-delay feedback, and asymmetric information structures guides autonomous vehicles.

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Jun 14, 2009 Liang Jin , M. M. Gupta, Stable dynamic backpropagation learning in 1, pp. 339 -356, 1998. 20. Qing Song , J. C. Spall , Yeng Chai Soh , Jie Ni, 27. V. Vapnik, Statistical learning theory, John Wiley and Sons, Inc. New York, 1998. neural fields can generate complex behavior in mobile robot navigation.

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Dynamics of Manipulation Robots: Theory and Application (Communications and Control Engineering / Scientific Fundamentals of Robotics) Softcover reprint of the

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