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By Chanel Ashby

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Jan 1, 2014 M.A. Aizerman, Lectures on the theory of automatic control, Fizmatgiz, Moscow, 1958.
Kuniyoshi, Cognitive developmental robotics as a new paradigm for 1- 29. br000155. Karl~J. A str m,
Early control development in Numerical identification of linear dynamic systems from normal operating
records.

Control information theory: the missing link in

Norbert Wiener's cybernetic paradigm represents one of the seminal ideas of the 20th century. organisms
with differentiated organ systems, in the behavioral dynamics of socially- robotics, in aerospace
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Performance of a SCARA Robot Manipulator With Uncertainty Using Polynomial Chaos Theory

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A two-wheeled self-balancing robot with a fuzzy PD control method is described and analyzed as an
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Models of information processing in the

Information Theory and Statistical Learning. pp 289- This allows one to formulate a consistent informational view of how an agent extracts information from the

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Robot as a new frontier for connectionism and

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Spatially random models, estimation theory, and

,tt Yl Spatially Random Models, Estimation Theory, and Robot Arm Dynamics G. Rodrigtwz Jet Propulsion Laboratory California Institute of Technology

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